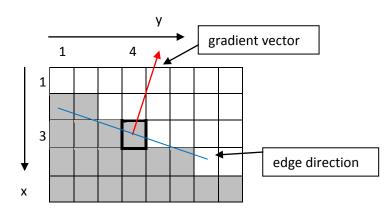


1.2 Gradient vector =  $[g_x g_y] = [-3 1]$ , gradient magnitude =  $\sqrt{10}$ 



## 2. 1-g, 2-j, 3-c, 4-h, 5-e

3.1 3-bits: GLCM: 8 x 8, 6 bits: GLCM size =  $2^6 x 2^6 = 64 x 64$ 3.2 Cooccurrence matrices: Left half image  $\approx$ 

$\begin{bmatrix} \frac{1}{16} & \frac{1}{16} & \frac{1}{16} & \frac{1}{16} \\ \frac{1}{16} & \frac{1}{16} & \frac{1}{16} & \frac{1}{16} \end{bmatrix}$ Right half-image:	$\begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 &$	$\begin{bmatrix} \frac{1}{32} \\ \frac{1}{32} \\ \frac{1}{32} \\ \frac{1}{32} \\ \frac{1}{32} \end{bmatrix}$	1	$ \begin{array}{r} 1 \\         32 \\         1 \\         32 \\         1 \\         32 \\         1 \\         32 \\         1 \\         32         32      $	$\frac{1}{32}$ $\frac{1}{32}$ $\frac{1}{32}$ $\frac{1}{32}$ $\frac{17}{32}$				
Textural entropy $\approx 2.83$ % -p*log2(p))									

## 3.3 The complex Fourier descriptors a(k) are defined as:

$$a(k) = \sum_{n=0}^{N-1} u(n) \exp\left(\frac{-j2pkn}{N}\right)$$

u(n) = X(n) + jY(n), where u(n) are the boundary points. **Translation invariancy of a(0)**:

$$a(0) = \sum_{n=0}^{N-1} u(n) \exp\left(\frac{-j2\pi \cdot 0 \cdot n}{N}\right) = \sum_{n=0}^{N-1} u(n)$$

Let's translate the object by vector (c, d). The new coordinates  $u_{new}(n)$  will become  $u_{new}(n) = X(n) + jY(n) + c + jd$ 

The new FDs will be:

 $a_{new}(0) = \sum_{n=0}^{N-1} [u(n) + c + jd] \exp\left(\frac{-j2\pi \cdot 0 \cdot n}{N}\right) = N \cdot (c + jd) + \sum_{n=0}^{N-1} u(n) = N \cdot (c + jd) + a(0)$  $a_{new}(0) \text{ is not equal the original } a(0) \to a(0) \text{ is } \textbf{NOT} \text{ translation invariant}$ 

## Translation invariancy of a(k), k>0:

$$a(k) = \sum_{n=0}^{N-1} u(n) \exp\left(\frac{-j2\pi \cdot k \cdot n}{N}\right)$$

Let's translate the object by vector (c, d). The new coordinates  $u_{new}(n)$  will become  $u_{new}(n) = X(n) + jY(n) + c + jd$ 

The new FDs will be:

This sum is equal zero.

 $a_{new}(k)$  is equal the original  $a(k) \rightarrow a(k)$ , k>0, is translation invariant

## **Rotation invariancy of** |a(i)|: $u_{new}(n) = [X(n) + jY(n)]\exp(j\theta)$

 $a_{new}(k) = \sum_{n=0}^{N-1} u(n) \cdot \exp(j\theta) \cdot \exp\left(\frac{-j2\pi k \cdot n}{N}\right) = \exp(j\theta) \cdot a(k)$   $|a_{new}(k)| = |\exp(j\theta) \cdot a(k)| = |\exp(j\theta)| \cdot |a(k)| = |a(k)|$ as  $|\exp(j\theta)| = 1$  for any  $\theta$ :  $|\exp(j\theta)| = |\cos(\theta) + j\sin(\theta)| = (\cos^2(\theta) + \sin^2(\theta))^{1/2} = 1$   $|a_{new}(k)| = |a(k)| \rightarrow \text{magnitude of FDs is rotationally invariant feature}$ 

4.1 After the first iteration we have three more samples inside the kernel--> the density (assuming uniform kernel) in this region will be higher than in the starting position of the kernel--> we are moving toward a more dense region (=ascending pdf)

4.2 The (estimate) of the joint probability density function of image attributes.

4.3 See the textbook, e.g. Sonka et al., Pages 259-263.

5.1

	1	2	3
1	20	121	20
2	12	12	15
3	♦6	12	14
4	6	10	15
5	4 👗	<u> </u>	11
6	4	5 🔺	7

5.2 To detect the line, the curves should cross each other (otherwise the line will not be detected).

