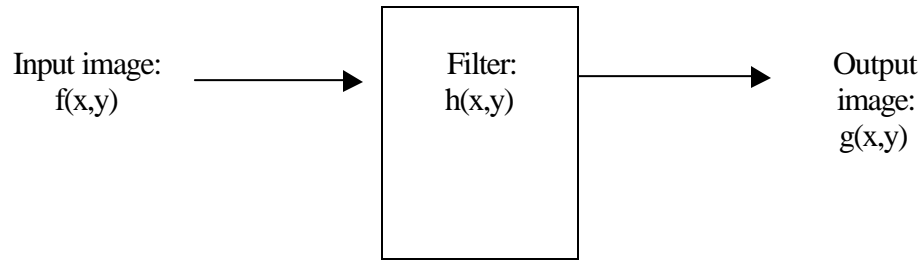


## CONVOLUTION



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### Convolution: continuous form

We define the convolution of  $f(x, y)$  by  $h(x, y)$  by the integral

$$g(x,y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(a,b) \cdot h(x-a, y-b) \cdot da \cdot db \quad (1)$$

### Convolution: discrete form

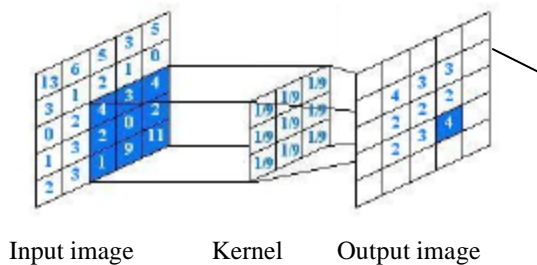
In the discrete form the convolution is defined as

$$g(x,y) = \sum_{a=-\infty}^{\infty} \sum_{b=-\infty}^{\infty} f(a,b) \cdot h(x-a, y-b) \quad (2)$$

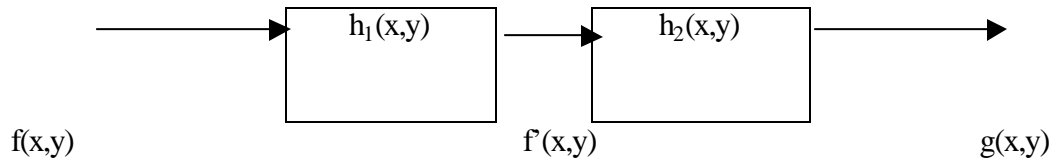
We denote convolution as

$$g(x,y) = f(x,y) * h(x,y)$$

### Convolution: example



### Convolution: multiple filters



$$\begin{aligned} f'(x,y) &= f(x,y) * h_1(x,y) \\ g(x,y) &= f'(x,y) * h_2(x,y) \\ &= \{f(x,y) * h_1(x,y)\} * h_2(x,y) \\ &= f(x,y) * \{h_1(x,y) * h_2(x,y)\} \end{aligned}$$

### Convolution: Equivalent terminology

- Impulse response
- Convolution kernel
- Mask
- Operator
- Filter